

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

$$\langle u, v \rangle = v^T u = u_1 v_1 + u_2 v_2$$

Gram-Schmidt process and QR factorization

- Let $\{u_1, \dots, u_k\} \subseteq \mathbb{R}^n$ be a linearly independent set. We can an orthonormal set $\{v_1, \dots, v_k\}$ by the Gram-Schmidt process as follows.

u_1, u_2, u_3

Let $v_1 = u_1$. If v_1, \dots, v_ℓ are constructed and $\ell < k$, set

$$\tilde{v}_{\ell+1} = u_{\ell+1} - (a_1 v_1 + \dots + a_\ell v_\ell) \quad \text{and} \quad v_{\ell+1} = \tilde{v}_{\ell+1} / \|\tilde{v}_{\ell+1}\|$$

with $a_j = \langle v_j, u_{\ell+1} \rangle$ for $j = 1, \dots, \ell$.

- As a result, we can construct an orthonormal basis for a subspace.

$$\begin{aligned} \langle u, v \rangle &= 0 \\ \Rightarrow u, v \text{ are orthogonal} & \end{aligned}$$

$$\|u\| \|v\| \cos \theta = \langle u, v \rangle$$

- Orthogonal subspaces. For example, row space and null space are orthogonal subspaces.

$$\langle v_i, v_j \rangle = 1 \quad \forall i, j$$

- Also, we have the QR factorization.

$$[u_1 | \dots | u_k] = [v_1 | \dots | v_k] R = QR$$

for an upper triangular matrix $R \in M_k$.

Example

$$u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad u_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad u_3 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\hat{v}_2 = u_2 - \alpha_1 v_1$$

s.t.

$$0 = \langle \hat{v}_2, v_1 \rangle = \langle u_2 - \alpha_1 v_1, v_1 \rangle = \langle u_2, v_1 \rangle - \alpha_1 \langle v_1, v_1 \rangle = \langle u_2, v_1 \rangle - \alpha_1$$

$$\therefore \alpha_1 = \frac{\langle u_2, v_1 \rangle}{\|v_1\|^2} = \frac{2}{\sqrt{2}}$$

$$\hat{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{2}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}, \quad v_2 = \frac{\hat{v}_2}{\|\hat{v}_2\|} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$$

Want:

$$u_3 = \hat{v}_3 + \alpha_1 v_1 + \alpha_2 v_2$$

$$0 = \langle \hat{v}_3, v_1 \rangle = \langle u_3, v_1 \rangle - \alpha_1 \langle v_1, v_1 \rangle - \alpha_2 \langle v_2, v_1 \rangle$$

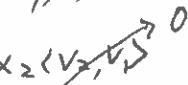
$$\alpha_1 = \langle u_3, v_1 \rangle$$

$$v_1 = u_1$$

$$\hat{v}_2 = u_2 - \alpha_1 v_1$$

$$0 = \langle \hat{v}_2, v_1 \rangle = \langle \hat{v}_2, u_2 \rangle - \alpha_1 \langle \hat{v}_2, v_1 \rangle$$

$$\approx 0 - \langle v_1, u_2 \rangle$$



Example (cont'd)

$$u_3 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad v_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{aligned} \tilde{v}_3 &= u_3 - \alpha_1 v_1 - \alpha_2 v_2 \\ &= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{3}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{3}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}. \end{aligned}$$

$$\therefore \tilde{v}_3 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{for } [v_1 \ v_2 \ v_3] = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{bmatrix}$$

Check

$$\begin{bmatrix} v_1^T \\ v_2^T \\ v_3^T \end{bmatrix} [v_1 \ v_2 \ v_3] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Remark: ~~If $\{v_1, \dots, v_k\} \subseteq \mathbb{R}^n$ is an orthonormal set~~

$$\Leftrightarrow \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} [v_1 \dots v_k] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \in M_k$$

Remark:

$$\textcircled{1} \quad \text{col} \begin{bmatrix} u_1 \dots u_j \end{bmatrix} = \text{col} \begin{bmatrix} v_1 \dots v_j \end{bmatrix}$$

In fact,

$$\begin{bmatrix} u_1 \dots u_j \end{bmatrix} = \begin{bmatrix} v_1 \dots v_j \end{bmatrix} \begin{bmatrix} R_{11} & R_{12} \\ 0 & R_{22} \\ \vdots & \vdots \\ 0 & 0 & \ddots & R_{jj} \end{bmatrix} \quad j \times j \quad \boxed{\times}$$

$$u_1 = r_{11}v_1$$

$$u_2 = r_{12}v_1 + r_{22}v_2$$

$$Q^T Q = I_j$$

\textcircled{2}

$$u_3 = - - -$$

$$\text{col} \begin{bmatrix} u_1 \dots u_k \end{bmatrix} = \text{col} \begin{bmatrix} v_1 \dots v_k \end{bmatrix}$$

\therefore the subspace in \mathbb{R}^n generated by $\{u_1 \dots u_k\}$ is the same as that generated by $\{v_1 \dots v_k\}$.

So $\{v_1 \dots v_k\}$ is an orthonormal basis.

In general every vector v in the subspace can be written as

$$v = \underline{\alpha_1} u_1 + \dots + \underline{\alpha_k} u_k \quad \left| \begin{bmatrix} u_1 \dots u_k \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_k \end{bmatrix} = v \right.$$

Also $v = \beta_1 v_1 + \dots + \beta_k v_k + 0$

$$\beta_j = \langle v, v_j \rangle, j=1, \dots, k$$

$$\begin{aligned} & \left[\begin{bmatrix} v_1 \dots v_k \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \right] \\ & \left[\begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \begin{bmatrix} v_1 \dots v_k \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \right] \\ & \left[\begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \begin{bmatrix} R_{11} & R_{12} \\ 0 & R_{22} \\ \vdots & \vdots \\ 0 & 0 & \ddots & R_{kk} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \right] \\ & \left[\begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} Q^T \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \right] \\ & Q^T \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \\ & \left[\begin{bmatrix} \beta_1 \\ \vdots \\ \beta_k \end{bmatrix} = Q \begin{bmatrix} v_1^T \\ \vdots \\ v_k^T \end{bmatrix} \right] \end{aligned}$$

$$\textcircled{1} \quad A =$$

$$\underline{QR}$$

$$\textcircled{2} \quad Ax = b$$

$$\textcircled{3} \quad QRx = b$$

$$\textcircled{4} \quad Rx = Q^T b$$

Remark: For \mathbb{C}^n , $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$, $y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$

$$\langle x, y \rangle = \bar{y}_1 x_1 + \dots + \bar{y}_n x_n \in \mathbb{C}$$

Example $\left\langle \begin{pmatrix} 1+i \\ i \\ 1 \end{pmatrix} \mid \begin{pmatrix} i \\ 1 \\ 2 \end{pmatrix} \right\rangle$

$$= (-i, 2) \begin{pmatrix} 1+i \\ i \\ 1 \end{pmatrix} = -i + 1 + 2^2 = -i + 3.$$

Still define $|\langle x, y \rangle| = \|x\| \|y\| \cos \theta$

Givran Schmidt works! $A = QR$, $Q^* Q = I_k$

R is $k \times k$

Example $u_1 = \begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}, u_2 = \begin{pmatrix} 1 \\ i \\ 1 \end{pmatrix}, u_3 = \begin{pmatrix} 1 \\ 2 \\ 3i \end{pmatrix}$ upper triangular.

$$v_1 = \frac{\begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}}{\sqrt{2}} \quad \hat{v}_2 = u_2 - \cancel{\alpha_1 v_1}, \quad \alpha_1 = \left\langle \begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}, \frac{\begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}}{\sqrt{2}} \right\rangle$$

$$= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\hat{v}_3 = \begin{pmatrix} 1 \\ 2 \\ 3i \end{pmatrix} - \alpha_1 v_1 - \alpha_2 v_2 \quad \alpha_1 = \langle u_3, v_1 \rangle$$

$$\alpha_2 = \langle u_3, v_2 \rangle$$

$$= (1+i) \begin{pmatrix} 1 \\ -i \\ 0 \end{pmatrix} \quad v_3 = \frac{\begin{pmatrix} i \\ -i \\ 0 \end{pmatrix}}{\sqrt{2}}$$

so $Q = [v_1 \ v_2 \ v_3]$

then $\textcircled{1} [u_1 \ u_2 \ u_3] = Q \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & r_{23} \\ 0 & 0 & r_{33} \end{bmatrix}, Q^* Q = I_3$

$$Q^* = (\bar{Q}^T) = (\bar{Q})^T$$

Special classes of matrices

$$Q^T Q$$

- Matrix $Q \in M_{n,m}$ with orthonormal columns. $\underline{Q^* Q = I_m}$. Then QQ^* is a projection.

Example:

$$P_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \end{bmatrix} / \sqrt{3} = \begin{bmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$P_2 = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- A matrix $Q \in M_n$ such that $Q^* Q = I_n$ is a unitary/orthogonal matrix.

The set of unitary / orthogonal matrices form a group.

$$Q^T Q = I$$

$$\Leftrightarrow Q Q^T = I$$

- Hadamard matrices.

If $n = 4k$, then there is a Hadamard matrix in $M_n(\mathbb{R})$.

The smallest unknown case: 668.

$$A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \quad A A^T = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \quad \frac{A}{\sqrt{2}} \cdot \frac{A^T}{\sqrt{2}} = \frac{AA^T}{2} = I$$

$$A \otimes A = \begin{bmatrix} A & A \\ A & -A \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & -1 & -1 & 1 \end{bmatrix}$$

$$(A \otimes A)(A \otimes A)^T = I_{16}$$

$$(A \otimes A) \otimes (A \otimes A)$$

$$(A \otimes A) \otimes (A \otimes A)$$

Kronecker product

$$(A \otimes A) \otimes A, \quad 8 \times 8 \quad 2^k$$

- Hadamard matrices are useful in quantum computing.

$A \otimes B$

$$[a_{ij}] \otimes B$$

$n=4$

$$\begin{bmatrix} a_{11}B & a_{12}B & a_{13}B \\ a_{21}B & \dots & a_{mn}B \end{bmatrix}$$

Householder reflection has the form $I - 2uu^*$ for a unit vector. The matrix has eigenvalues $-1, 1, \dots, 1$.

$m \times n \quad P \times R \quad n \times r \times s$

$$(A \otimes B)(C \otimes D) = (A \cdot C) \otimes (BD)$$

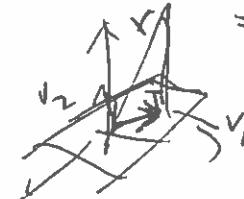
$$\begin{pmatrix} m \times n \\ \vdots \\ 1 \end{pmatrix} \otimes \begin{pmatrix} r \times s \\ \vdots \\ 1 \end{pmatrix}$$

$$mp \times rs = X = a_1(A_1 \otimes B_1)(C_1 \otimes D_1) + a_2(A_2 \otimes B_2)(C_2 \otimes D_2) + \dots$$

$$V_3 V_3^T = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 \end{bmatrix} / \sqrt{3} = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & 0 \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$(V_1 V_2) [V_1^T \ V_2^T] = \begin{bmatrix} V_1 V_2 \\ V_1^T V_2^T \end{bmatrix} = \begin{bmatrix} V_1 V_2 \\ V_1^T V_2^T \end{bmatrix}$$

$$= \alpha_1 V_1 + \alpha_2 V_2$$



$$m \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} = S_1 \begin{bmatrix} \vdots & \vdots & \vdots \\ \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots \end{bmatrix} + S_2 \begin{bmatrix} \vdots & \vdots & \vdots \\ \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots \end{bmatrix} + \dots$$

Example

$$u_1 = \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} \quad u_2 = \begin{bmatrix} 1 \\ i \\ 1 \end{bmatrix} \quad u_3 = \begin{bmatrix} 1 \\ 2 \\ 3i \end{bmatrix}$$

Remark

$$u_1 = \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ i \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 2 \\ 3i \end{bmatrix}$$

$$\langle x, y \rangle = x_1 \bar{y}_1 + x_2 \bar{y}_2 + x_3 \bar{y}_3$$

$$\begin{aligned} v_1 &= \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} \quad \hat{v}_2 = u_2 - \langle u_2, v_1 \rangle v_1 \\ &= u_2 - \frac{(1-i)(\begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix})}{\sqrt{2}} \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} \\ &= u_2 - \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \hat{v}_3 &= u_3 - \langle u_3, v_1 \rangle v_1 - \langle u_3, v_2 \rangle v_2 \\ &= \begin{bmatrix} 1 \\ 2 \\ 3i \end{bmatrix} - \frac{(1-i)(\begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix})}{\sqrt{2}} \begin{bmatrix} 1 \\ i \\ 0 \end{bmatrix} - (0 \ 0 \ -1) \begin{pmatrix} 1 \\ 2 \\ 3i \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \\ &= \begin{bmatrix} 1 \\ 2 \\ 3i \end{bmatrix} - \frac{1+2i}{\sqrt{2}} \begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix} - (3i) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \left(1 + \frac{i}{2}\right) \begin{pmatrix} 1 \\ -i \\ 0 \end{pmatrix} \end{aligned}$$

$$\begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}$$

$$\textcircled{2} \ 1 - \frac{1}{2} + \frac{2i}{2}$$

$$x = \frac{1}{2} + i$$

$$2-1$$

$$i$$

$$v_3 =$$

$$\begin{pmatrix} 1 \\ -i \\ 0 \end{pmatrix}$$

$$\frac{1}{\sqrt{2}}$$