

**Differential equations.** Consider the system  $Ax' = x$  with  $x(0) = x_0$ .

For one variable,  $x' = ax$  with  $x(0) = x_0$ , we have  $x = e^{at}x_0$ .

Suppose  $S^{-1}AS = D = \text{diag}(d_1, \dots, d_n)$ . Then

$$A = SDS^{-1} = d_1 S(:, 1) S^{-1}(1, :) + \dots + d_n S(:, n) S^{-1}(n, :).$$

For  $y = Sx$ ,  $Sx' = y'$  and  $Dy' = y$  so that

$$y = e^{Dt} y_0 = \begin{bmatrix} e^{id_1 t} & & \\ & \ddots & \\ & & e^{id_n t} \end{bmatrix} y_0 \quad \text{and} \quad x = S^{-1}y = S^{-1}e^{Dt}Sx_0.$$

That is,

$$x = (e^{d_1 t} S(:, 1) S^{-1}(1, :) + \dots + e^{d_n t} S(:, n) S^{-1}(n, :)) x_0.$$

**Example:** Solve  $x' = Ax$  with  $A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  and  $x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ . Then  $A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = SDS^{-1}$  with

$D = \text{diag}(\lambda_1, \lambda_2) = \text{diag}((1 + \sqrt{5})/2, (1 - \sqrt{5})/2)$  and

$$S = \begin{bmatrix} 1 & (\sqrt{5}-1)/2 \\ (\sqrt{5}-1)/2 & -1 \end{bmatrix} \quad \text{and} \quad S^{-1} = \frac{2}{5-\sqrt{5}} S.$$

So,

$$x = \frac{1}{\sqrt{5}} \begin{bmatrix} \lambda_1 e^{\lambda_1 t} - \lambda_2 e^{\lambda_2 t} \\ e^{\lambda_1 t} - e^{\lambda_2 t} \end{bmatrix}.$$

In fact, one can solve the equation  $x'' = x' + x$  with  $x(0) = (1, 0)^T$ .

Now,  $\begin{pmatrix} x' \\ x \end{pmatrix}' = A \begin{pmatrix} x' \\ x \end{pmatrix}$  so that  $x = \frac{1}{\sqrt{5}} e^{\lambda_1 t} - e^{\lambda_2 t}$ .

**Exercise** Solve the system  $x' = Ax$  with the above  $A$  and  $x_0 = (2, 1)^T$ .

$$x_i'(t) = a_{11}x_1(t) + a_{12}x_2(t)$$

$$x_2'(t) = a_{21}x_1(t) + a_{22}x_2(t)$$

$$y_1'(t) = \lambda_1 y_1(t)$$

$$y_n'(t) = \lambda_n y_n(t)$$

$$x(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}$$

$$x_1'(t) = x_1(t) + x_2(t)$$

$$x_2'(t) = x_1(t)$$

$$\begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix} = S^{-1} \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}$$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = S \begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix}$$

# Differential equation:

Solve

$$y_1'(t) = \lambda_1 y_1$$

$$y_2'(t) = \lambda_2 y_2$$

⋮

$$y_n'(t) = \lambda_n y_n$$

Given  $y_j(0)$ ,  $j=1, \dots, n$

Then

$$y_j(t) = e^{\lambda_j t} y_j(0)$$

$$x' = Ax + \begin{matrix} O(x^2) \\ A(t^2)x \end{matrix}$$

$$x_1'(t) = a_{11} x_1(t) + \dots + a_{1n} x_n(t)$$

$$x_2'(t) = a_{21} x_1(t) + \dots + a_{2n} x_n(t)$$

⋮

$$x_n'(t) = a_{n1} x_1(t) + \dots + a_{nn} x_n(t)$$

$$x'(t) = Ax(t)$$

$$A = SDS^{-1}, D = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$$

$$x'(t) = SDS^{-1} x(t)$$

$$y = S^{-1} x(t) \quad \parallel \quad S^{-1}$$

$$(S^{-1} x'(t)) = D(S^{-1} x(t))$$

$$\begin{pmatrix} y_1(t) \\ \vdots \\ y_n(t) \end{pmatrix} = \begin{pmatrix} b_{11} & \dots & b_{1n} \\ b_{21} & \dots & b_{2n} \\ \vdots & & \vdots \\ b_{n1} & \dots & b_{nn} \end{pmatrix} \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix}$$

$$y'(t) = Dy(t)$$

$$S \begin{pmatrix} y_1(t) \\ \vdots \\ y_n(t) \end{pmatrix} = \begin{pmatrix} x_1(t) \\ \vdots \\ x_n(t) \end{pmatrix}$$

$$\begin{pmatrix} y_1'(t) \\ \vdots \\ y_n'(t) \end{pmatrix} = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \begin{pmatrix} y_1(t) \\ \vdots \\ y_n(t) \end{pmatrix}$$

$$y_j'(t) = [b_{j1} x_1(t) + \dots + b_{jn} x_n(t)]' \\ = b_{j1} x_1'(t) + \dots + b_{jn} x_n'(t)$$

$$(y^{(n)})' = a_1 y^{(n)} + a_2 y^{(n-1)} + \dots + a_{n+1} y^{(0)}$$

$$\begin{pmatrix} (y^{(n)}) \\ (y^{(n-1)}) \\ \vdots \\ (y^{(0)}) \end{pmatrix}' = \begin{pmatrix} a_1 & a_2 & \dots & a_{n+1} \\ 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 1 & 0 \end{pmatrix} \begin{pmatrix} y^{(n)} \\ \vdots \\ y^{(0)} \end{pmatrix}$$

(n+1)

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$$= \begin{pmatrix} S & D & S^{-1} \\ \varphi \end{pmatrix} \begin{pmatrix} y^{(n)} \\ \vdots \\ y^{(0)} \end{pmatrix}$$

Solve

$$\begin{pmatrix} \hat{y}^{(n)} \\ \vdots \\ \hat{y}^{(0)} \end{pmatrix} = \begin{pmatrix} e^{\lambda_1 t} \hat{y}^{(0)} \\ \vdots \\ e^{\lambda_n t} \hat{y}^{(0)} \end{pmatrix}$$

Then recover ~~y(t)~~

where

$$\begin{pmatrix} \hat{y}^{(n)} \\ \vdots \\ \hat{y}^{(0)} \end{pmatrix} = S^{-1} \begin{pmatrix} y^{(n)} \\ \vdots \\ y^{(0)} \end{pmatrix}$$

$$\begin{pmatrix} y^{(n)} \\ \vdots \\ y^{(0)} \end{pmatrix} = S \begin{pmatrix} \hat{y}^{(n)} \\ \vdots \\ \hat{y}^{(0)} \end{pmatrix}$$

$$A = A^T \text{ symmetric}$$

$$a_{ij} = a_{ji} \quad \begin{pmatrix} 1 & 3 \\ 3 & 4 \end{pmatrix}$$

1.7 Symmetric matrices, Hermitian matrices, positive definite matrices

Theorem (a) Every real symmetric matrix  $A$  can be written as  $QDQ^T$  for a real diagonal matrix  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$  and an orthogonal matrix  $Q$ .

(b) Every complex Hermitian matrix  $A$  can be written as  $UDU^*$  for a real diagonal matrix  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$  and a unitary matrix  $U$ .

Proof. If  $A \in M_2(\mathbb{R})$  be symmetric, let  $v = [v_1, v_2]^T \in \mathbb{R}^2$  be such that  $v^T v = 1$  and

$$v^T A v = \lambda_1 = \max\{x^T A x : x \in \mathbb{R}^2, x^T x = 1\}$$

Then  $Q = \begin{pmatrix} v_1 & v_2 \\ v_2 & -v_1 \end{pmatrix}$  is orthogonal, and we claim that  $Q^T A Q = \text{diag}(\lambda_1, \lambda_2)$ . If not, assume

$$Q^T A Q = \begin{pmatrix} \lambda_1 & b \\ b & c \end{pmatrix}$$

$$f(t) = a_{11} \cos^2 t + 2a_{12} \cos t \sin t + a_{22} \sin^2 t$$

$$f(\theta) = [\cos \theta, \sin \theta] Q^T A Q [\cos \theta, \sin \theta]^T = \cos^2 \theta \lambda_1 + 2 \cos \theta \sin \theta b + \sin^2 \theta c$$

$t \in [0, 2\pi]$

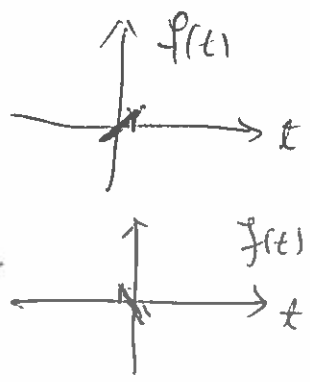
and  $f'(0) = 2b \neq 0$ . So, we can find  $\theta$  near 0 such that  $u^T A u > \lambda_1$  with  $u = Q[\cos \theta, \sin \theta]^T$ , which is a contradiction.

Now, for  $A \in M_n(\mathbb{R})$ . Let  $v \in \mathbb{R}^n$  be a unit vector such that

$$v^T A v = \lambda_1 = \max\{x^T A x : x \in \mathbb{R}^n, x^T x = 1\}$$

Suppose  $Q$  is an orthogonal matrix such that  $Q^T A Q = A_1$ . Then  $A_1 = [\lambda_1] \oplus A_2 \dots$

(cont  $\sin t$ )  
( $\sin t - \cos t$ )



$\therefore$  For  $A \in M_2(\mathbb{R})$ ,  $\exists Q$  s.t.

$$Q^T A Q = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \quad \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} Q^T A Q \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \lambda_1$$

For  $n > 2$  consider  $v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ ,  $v_1^2 + \dots + v_n^2 = 1$

$$\text{let } v^T A v = \lambda_1 = \max_{x^T x = 1} x^T A x$$

For the complex case, we consider a unit vector  $v \in \mathbb{C}^n$  such that

$$v^* A v = \lambda_1 = \max\{u^* A u : u \in \mathbb{C}^n, u^* u = 1\}$$

Let  $Q = [v | v_2 | \dots | v_n]$  be orthogonal. See note.

Then  $Q^T A Q = \begin{bmatrix} \lambda_1 & 0 \\ 0 & A_1 \end{bmatrix}$ . See note. By induction on  $A_1$

Remark.

$$AS = S \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{bmatrix},$$

$$S^{-1}AS = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{bmatrix} = D$$

$$A = SDS^{-1}$$

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Example

$$A = \begin{bmatrix} 2 & 3 \\ 0 & 1 \end{bmatrix}$$

$$0 = \det(\lambda I - A) = \det \begin{pmatrix} \lambda - 2 & -3 \\ 0 & \lambda - 1 \end{pmatrix} = \det(A) = (\lambda - 2)(\lambda - 1)$$

$$S = [v_1 \ v_2] \text{ s.t.}$$

$$AS = [Av_1 \ Av_2] = [v_1 \ v_2] \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$S^{-1}AS = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

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If there <sup>were</sup> ~~is~~ an orthogonal  $Q$  s.t.

$$Q^T A Q = Q^T A Q = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 3 \\ 0 & 1 \end{bmatrix} = A = Q \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} Q^T$$

$$\begin{aligned} \left( Q \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} Q^T \right)^T &= (Q^T)^T \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}^T Q^T \\ &= \underline{Q \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} Q^T} \end{aligned}$$

Note for explaining the proof

① let

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$$

$$v = \frac{\begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}}{\sqrt{1^2 + 2^2 + 3^2}} \quad \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

↯ apply Gram-Schmidt

Find  $v_2, v_3$  s.t

$\begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix}$  is orthogonal.

②

$$Q^T A Q = \begin{bmatrix} \lambda_1 & 0 & 0 & c \cos \theta \\ 0 & \vdots & \vdots & \vdots \\ 0 & c \sin \theta & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix} \quad c \neq 0$$

↓  $j$ th

consider  $\begin{pmatrix} \lambda_1 & c \\ c & d \end{pmatrix} \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = \lambda_1 + \epsilon > \lambda_1$

$$\underbrace{\begin{bmatrix} \cos \theta & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & c \sin \theta & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}}_{j\text{th}} Q^T A Q \begin{bmatrix} \cos \theta \\ \vdots \\ \sin \theta \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ c & d \end{bmatrix} \begin{bmatrix} c \cos \theta \\ \sin \theta \end{bmatrix} = \lambda_1 + \epsilon$$

$\|Qx\|^2 = x^T Q^T Q x = x^T I x = x^T x = \|x\|^2$

$$S^{-1}AS = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \quad A = S \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} S^{-1}$$

$$Q^T A Q = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \quad A = A^T \quad A = Q \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} Q^T$$

**Positive (semi)definite matrices.**

**Definition** A real symmetric matrix  $A \in M_n(\mathbb{R})$  is positive definite (semi-definite) if it has positive (nonnegative) eigenvalues  $\Leftrightarrow A = Q \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{bmatrix} Q^T, \lambda_1, \dots, \lambda_n > 0$

A complex Hermitian matrix  $A \in M_n(\mathbb{C})$  is positive definite (semi-definite) if it has positive (nonnegative) eigenvalues

**Equivalent conditions**

1.  $x^* A x > 0$  for all nonzero vector  $x$ .

$$x^T A x \in \mathbb{R} \Rightarrow A \text{ is symmetric}$$

2.  $S = A^* A$  for an invertible  $A$ .

3.  $A$  has positive leading principal minors meaning ...

4. All pivots of  $A$  are positive. [In the Gaussian elimination process.] Then  $A = LDL^*$  or  $A = \tilde{L}\tilde{L}^*$  for some invertible lower triangular matrix  $\tilde{L}$ , the Cholesky factorization.

**Example.**  $A = \begin{pmatrix} 4 & 3 \\ 3 & 4 \end{pmatrix}$ .

**Applications 1.** Maximum and minimum of real valued function  $f(x_1, \dots, x_n)$ .

2. Major and minor axes of elliptical disk/ellipsoid.

$A = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  is not positive definite

$B = \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix}$  is not positive semi-definite

For  $C = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$  both  $C$  &  $-C$  are not positive semi-definite

$F = \begin{pmatrix} 0 & 2 \\ 2 & 4 \end{pmatrix}$

$$\det(F) = -4 = \lambda_1 \lambda_2$$

$$F = Q \Lambda Q^T \Rightarrow \Lambda = Q \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} Q^T$$

$$\det(F) = \det(Q) \det(\Lambda) \det(Q^T) = \det(Q) \det(Q^T) \lambda_1 \lambda_2 = \det(QQ^T) \lambda_1 \lambda_2 = \det(I) \lambda_1 \lambda_2 = \lambda_1 \lambda_2$$

Note :

$$\text{If } A = S \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix} S^{-1}$$

$$\text{Then } \text{trace } A = a_{11} + \dots + a_{nn} = \lambda_1 + \dots + \lambda_n$$

$$\det(A) = \lambda_1 \dots \lambda_n$$

Proof :

$$\begin{aligned} \det(A) &= \det(S) \det \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix} \det(S^{-1}) \\ &= (\lambda_1 \dots \lambda_n) \det(S) \det(S^{-1}) \\ &= (\lambda_1 \dots \lambda_n) \det(SS^{-1}) \\ &= (\lambda_1 \dots \lambda_n) \det(I_n) \\ &= (\lambda_1 \dots \lambda_n) \end{aligned}$$

Note that

$$\begin{aligned} \text{trace} \left( (x_{ij}) (y_{ij}) \right) &= \sum_{i=1}^n \sum_{j=1}^n x_{ij} y_{ji} \\ &= \text{trace} \left( (y_{ij}) (x_{ij}) \right) \end{aligned}$$

$$\begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix}$$

$$= x_{11}y_{11} + x_{12}y_{21} + x_{21}y_{12} + x_{22}y_{22}$$

$$= \sum_{i=1}^2 \sum_{j=1}^2 x_{ij} y_{ji}$$

$$= (y_{ij}) (x_{ij})$$

$$c', = \text{trace } A = a_{11} + \dots + a_{nn}$$

$$= \text{trace} \left( S \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix} S^{-1} \right)$$

$$= \text{trace} \left( S^{-1} S \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix} \right)$$

$$= \text{trace} \left( I \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix} \right)$$

$$= \text{trace} \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix}$$

$$= \lambda_1 + \dots + \lambda_n$$



Given  $A = A^T \in M_n(\mathbb{R})$  has <sup>all</sup> positive values

Then  $A = Q \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} Q^T$   $\lambda_1, \dots, \lambda_n > 0$

~~$x^T A x$~~   $x^T A x = x^T Q \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} Q^T x$

$= [y_1 \dots y_n] \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2 > 0$

$\therefore x^T A x > 0 \quad \forall x \neq 0$

$y_1, \dots, y_n$  are not all zero

$\| \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \| = \| \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \| \neq 0$

$\exists x^T A x > 0 \quad \forall x \neq 0$

$\therefore A$  has <sup>all</sup> positive eigenvalues

Prove the contra-positive: Show if  $A$  has a non-positive eigenvalue  $\lambda$ .

Let  $x \neq 0$  be s.t.  ~~$Ax = \lambda x$~~

$Ax = \lambda x \quad \lambda \leq 0$

Then  $x^T A x = x^T \lambda x = \lambda \|x\|^2 \leq 0$

$\therefore x^T A x \not> 0$