

**Remarks**

$$|x\rangle = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \quad \begin{matrix} \frac{1}{\sqrt{2}}^2 \text{ prob } \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ \frac{1}{\sqrt{2}}^2 \text{ prob } \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{matrix}$$

But  $\frac{1}{\sqrt{2}}(|x\rangle + |y\rangle)$   
 $\neq \alpha_1|u_1\rangle + \alpha_2 e^{it}|u_2\rangle$

1. The phase of the state does not matter, i.e.,  $|x\rangle$  and  $e^{i\alpha}|x\rangle$  represents the same states.
2. In the finite dimensional case, if the state and the observable are represented by

$$|x\rangle = \sum_{j=1}^n c_j |u_j\rangle \in \mathbb{C}^n \quad \text{and} \quad A = \sum_{j=1}^n \lambda_j |u_j\rangle \langle u_j| = \sum_{j=1}^n \lambda_j P_j,$$

then the projective measurement of the state is

$$\langle x|A|x\rangle = \sum_{j=1}^n \lambda_j |c_j|^2.$$

$$= \sum_{\alpha} \alpha P_{\alpha}$$

Once the measurement is applied, the state becomes (collapses to)

$$\frac{P_i|x\rangle}{\sqrt{\langle x|P_i|x\rangle}} = \frac{P_i|x\rangle}{|c_i|}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{matrix} x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ x_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{matrix}$$

3. In the Schrödinger equation, if  $H(t)$  does not depend on  $t$ , then

$$|x(t)\rangle = e^{-iHt/\hbar} |x(0)\rangle.$$

Otherwise,

$$|x(t)\rangle = \exp\left(\frac{-i}{\hbar} \int_0^t H(s) ds\right) |x(0)\rangle.$$

**Example If**

$$H = \frac{-\hbar}{2} \omega \sigma_x \quad \text{and} \quad |\psi(0)\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{so that} \quad i\hbar \frac{\partial |\psi\rangle}{\partial t} = H|\psi\rangle,$$

then  $|\psi(t)\rangle = \exp(i\frac{\omega}{2}\sigma_x t) |\psi(0)\rangle$ . Hence,

$$|\psi(t)\rangle = \left( (\cos \omega t/2) I_2 + (i \sin \omega t/2) \sigma_x \right) |\psi(0)\rangle = \begin{pmatrix} \cos \omega t/2 \\ i \sin \omega t/2 \end{pmatrix}$$

$$\begin{pmatrix} \cos \omega t/2 & -i \sin \omega t/2 \\ i \sin \omega t/2 & \cos \omega t/2 \end{pmatrix}$$

$$i\hbar \begin{pmatrix} \psi_1'(t) \\ \psi_2'(t) \end{pmatrix} = \frac{-\hbar}{2} \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix} \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix} = -\frac{\hbar}{2} \begin{pmatrix} h_{11} \psi_1(t) + h_{12} \psi_2(t) \\ h_{21} \psi_1(t) + h_{22} \psi_2(t) \end{pmatrix}$$

$$x'(t) = kx(t)$$

$$x(t) = e^{+kt} x(0)$$

$$U \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix} = U \begin{pmatrix} e^{i\frac{\omega}{2}t} & 0 \\ 0 & e^{-i\frac{\omega}{2}t} \end{pmatrix} \begin{pmatrix} \psi_1(0) \\ \psi_2(0) \end{pmatrix}$$

$$U + i\frac{\hbar}{2} \begin{pmatrix} \psi_1'(t) \\ \psi_2'(t) \end{pmatrix} = -\frac{\hbar}{2} \begin{bmatrix} d_1 & \\ & d_2 \end{bmatrix} U \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix}$$

$$i\frac{\hbar}{2} \begin{pmatrix} \psi_1'(t) \\ \psi_2'(t) \end{pmatrix} = -\frac{\hbar}{2} \begin{pmatrix} d_1 & 0 \\ 0 & d_2 \end{pmatrix} \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix}$$

Two ways to compute

$$\exp(B) \quad \text{with} \quad B = (i\omega t/2)\sigma_x = (i\omega t/2) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

Method 1. Use the fact that

$$B = (i\omega t/2)\sigma_x = (i\omega t/2)P_1 + (-i\omega t/2)P_2 \quad \text{with} \quad P_1 = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, P_2 = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}.$$

Thus,

$$\exp(B) = e^{i\omega t/2}P_1 + e^{-i\omega t/2}P_2 = \frac{1}{2} \begin{pmatrix} e^{i\omega t/2} + e^{-i\omega t/2} & e^{i\omega t/2} - e^{-i\omega t/2} \\ e^{i\omega t/2} - e^{-i\omega t/2} & e^{i\omega t/2} + e^{-i\omega t/2} \end{pmatrix} = \begin{pmatrix} \cos(\omega t/2) & i \sin(\omega t/2) \\ i \sin(\omega t/2) & \cos(\omega t/2) \end{pmatrix}.$$

Method 2. Use the fact that  $\sigma_x^n = I_2$  if  $n$  is even, and  $\sigma_x^n = \sigma_x$  if  $n$  is odd. Then

$$\exp(B) = \sum_n B^n/n! = \sum_{2j} B^{2j}/(2j)! + \sum_{2j-1} B^{2j-1}/(2j-1)! = \cos(\omega t/2)I_2 + i \sin(\omega t/2)\sigma_x.$$

**The uncertainty principle**

Let  $\text{Exp}_x(A) = \langle x|A|x \rangle = \mu$  and

$$\left(\frac{1}{\sqrt{5}} \frac{1}{\sqrt{2}}\right) \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{5}} \end{bmatrix} = \frac{2}{\sqrt{2}} \frac{1}{\sqrt{2}} = \frac{3}{2}$$

$$\text{Var}_x(A) = \text{Exp}_x((A - \mu I)^2) = \langle x|(A - \mu I)^2|x \rangle = \|(A - \mu I)|x\rangle\|^2.$$

In an deterministic model, the variance of measurements should go to zero as the apparatus is made very accurate.

**Theorem** For any observable  $A$  and  $B$  and for any state  $|x\rangle$ , we have

$$\text{Var}_x(A)\text{Var}_x(B) \geq \frac{1}{4} \langle x|[A, B]|x \rangle,$$

where  $[A, B] = AB - BA$  is the commutator of  $A$  and  $B$ .

## Bipartite systems

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A system may have two components described by two Hilbert spaces  $\mathcal{H}_1$  and  $\mathcal{H}_2$ . Then the bipartite system is represented by  $\mathcal{H} = \mathcal{H}_1 \otimes \mathcal{H}_2$ . A general state in  $\mathcal{H}$  has the form

$$|x\rangle = \sum_{i,j} c_{ij} |e_{1,i}\rangle \otimes |e_{2,j}\rangle \quad \text{with} \quad \sum_{i,j} |c_{ij}|^2 = 1,$$

where  $\{|e_{r,1}\rangle, |e_{r,2}\rangle, \dots\}$  is an orthonormal basis for  $\mathcal{H}_r$  with  $r \in \{1, 2\}$ .

A state of the form  $|x\rangle = |x_1\rangle \otimes |x_2\rangle$  is a separable state or a tensor product state. Otherwise, it is an entangled state.

**Theorem** Every state  $|x\rangle$  in  $\mathcal{H}_1 \otimes \mathcal{H}_2$  admits a Schmidt decomposition

$$|x\rangle = \sum_{j=1}^r \sqrt{s_j} |u_j\rangle \otimes |v_j\rangle, \quad \rightarrow \quad r \leq \min \{ \dim \mathcal{H}_1, \dim \mathcal{H}_2 \} \\ = \min \{ m, n \}$$

where  $s_j > 0$  are the Schmidt coefficients satisfying  $\sum_{j=1}^r s_j = 1$ ,  $r$  is the Schmidt number of  $|x\rangle$ ,  $\{|u_1\rangle, \dots, |u_r\rangle\}$  is an orthonormal set of  $\mathcal{H}_1$  and  $\{|v_1\rangle, \dots, |v_r\rangle\}$  is an orthonormal set of  $\mathcal{H}_2$ .

**Remark** Extending the results to  $\mathcal{H}_1 \otimes \dots \otimes \mathcal{H}_k$  for  $k \geq 3$  is an open problem.

### Bipartite system

$$\left. \begin{aligned} |u\rangle &= \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \\ |v\rangle &= \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \end{aligned} \right\} |u\rangle \otimes |v\rangle = \begin{pmatrix} u_1 v_1 \\ u_1 v_2 \\ u_2 v_1 \\ u_2 v_2 \end{pmatrix}$$

more generally

$$\begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{pmatrix} \otimes \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} u_1(w_1) \\ u_2(w_1) \\ u_3(w_1) \\ u_4(w_1) \\ u_1(w_2) \\ u_2(w_2) \\ u_3(w_2) \\ u_4(w_2) \end{pmatrix}$$

Example.

$$|4\rangle = \frac{1}{\sqrt{1+4+1+6}} \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}$$

$$= \sqrt{5} |u\rangle \otimes |v\rangle + \sqrt{3} |u\rangle \otimes |v\rangle$$

$s_1^2 + s_2^2 = 1$

$$\in \mathbb{C}^2 \otimes \mathbb{C}^2 \cong \mathbb{C}^4$$

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set of all linear combinations of  
 $x \otimes y$   $x \in \mathbb{C}^2$   
 $y \in \mathbb{C}^2$ .

$$\{e_{1,1}, e_{1,2}\} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \text{ for } H_1$$

$$\{e_{2,1}, e_{2,2}\} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \text{ for } H_2$$

$$\{e_{i,j} \otimes e_{j,k} : (i,j) \neq (j,k), i, k \leq 2\}$$

$$= \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ is a basis for } \mathbb{C}^4$$

"  
 $\mathbb{C}^2 \otimes \mathbb{C}^2$

Schmidt decomposition = SVD.

$$\text{Let } |x\rangle = \sum_{i,j} c_{ij} |e_{1,i}\rangle \otimes |e_{2,j}\rangle.$$

where  $\{|e_{1,1}\rangle, \dots, |e_{1,m}\rangle\}$  is a basis for  $\mathcal{H}_1 \cong \mathbb{C}^m$   
 $\{|e_{2,1}\rangle, \dots, |e_{2,n}\rangle\}$  is a basis for  $\mathcal{H}_2 \cong \mathbb{C}^n$ .

Consider

$m \times n$  matrix

$$\begin{aligned} [c_{ij}] &= U \begin{bmatrix} \sqrt{s_1} & 0 & \dots & 0 \\ 0 & \sqrt{s_m} & & 0 \\ & & & 0 \end{bmatrix} V^\dagger \\ &= [u_1 | \dots | u_m] \begin{bmatrix} \sqrt{s_1} & 0 \\ 0 & \sqrt{s_m} \end{bmatrix} \begin{bmatrix} |v_1\rangle \\ \vdots \\ |v_m\rangle \end{bmatrix} \\ &= \text{~~U V~~} \end{aligned}$$

Then  $|x\rangle = \sqrt{s_1} |u_1\rangle \otimes |v_1\rangle + \dots + \sqrt{s_m} |u_m\rangle \otimes |v_m\rangle$

Example.

$$C = \frac{1}{2} \begin{pmatrix} 1 & 0 & i \\ 1 & 0 & i \end{pmatrix}$$

$$\begin{aligned} |x\rangle &= \frac{1}{2} (|e_{1,1}\rangle \otimes |e_{2,1}\rangle + \\ & |e_{1,1}\rangle \otimes |e_{2,3}\rangle + \\ & |e_{1,2}\rangle \otimes |e_{2,1}\rangle + \\ & |e_{1,2}\rangle \otimes |e_{2,3}\rangle) \end{aligned}$$

$$= \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$|x\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \otimes \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$